|   |   | Walc  | hand College  | of Engineering, Sa                  | noli      |         |  |  |  |  |
|---|---|---|---|-------------------------------------|-----------|---------|--|--|--|--|
|   |   | vv arc.   |   | d Autonomous Institute)             | iigii     |         |  |  |  |  |
| AY 2023-24  |   |   |   |                                     |           |         |  |  |  |  |
|   |   |   | Course 1  | Information                         |           |         |  |  |  |  |
| Progra  |   |   |   | M. Tech. (Power System Engineering) |           |         |  |  |  |  |
|   | Semester  |   | First Year M. Tec   | ch., Sem II                         |           |         |  |  |  |  |
| Course Code   |   |   | 7OE506  |                                     |           |         |  |  |  |  |
| Course Name   |   |   | Open Elective: Control Techniques for Electrical Drives   |                                     |           |         |  |  |  |  |
| Desire  | ed Requisit   | tes:  | M. Tech. (Power   | System Engineering)                 |           |         |  |  |  |  |
|   | Teaching  | Scheme  |   | <b>Examination Schem</b>            | e (Marks) |         |  |  |  |  |
| Lectu   |   | 3 Hrs/week  | MSE   | ISE                                 | ESE       | Total   |  |  |  |  |
| Tutori  | ial   |   | 30  | 20                                  | 50        | 100     |  |  |  |  |
|   |   |   |   | Credits: 3                          |           |         |  |  |  |  |
|   |   |   |   |                                     |           |         |  |  |  |  |
|   | Course Objectives   |   |   |                                     |           |         |  |  |  |  |
| 1   | Electric I  | o make students understand concept of fundamental knowledge in dynamics and control of ectric Drives.   |   |                                     |           |         |  |  |  |  |
| 2   |   | o strengthen control principles of various DC and AC motors using solid state converters.               |   |                                     |           |         |  |  |  |  |
| 3   | To cover Drives.  | o cover principles of selection of Electric Motors and highlights the applications of Electrical rives. |   |                                     |           |         |  |  |  |  |
|   | <u>'</u>  | Course  | Outcomes (CO) w   | ith Bloom's Taxonomy                | Level     |         |  |  |  |  |
| At the  | end of the  | course, the stud  | ents will be able to  | ),                                  |           | Bloom's |  |  |  |  |
| CO  |   | Course Outcome Statement/s  Bloom's  Taxonomy  Level  |   |                                     |           |         |  |  |  |  |
| CO1   | Explain t   | Explain the various concepts used in Electric drives.   |   |                                     |           |         |  |  |  |  |
| CO2   | Apply the   | Apply the control techniques for Electric drives for speed control.                                     |   |                                     |           |         |  |  |  |  |
|   | Analyze   | the performance   | ce of various cont  | rol techniques used in              |           |         |  |  |  |  |
| CO3   | speed co  | speed control of electric drives and select a drive for particular IV                                   |   |                                     |           |         |  |  |  |  |
|   | application   | pplication.   |   |                                     |           |         |  |  |  |  |
| Modu  | Module Contents   |   |   |                                     |           | Hours   |  |  |  |  |
| I   | Fundamentals of Electric Drives  Types & parts of the Electrical drives, Selection criteria of drives, motor rating, selection based on duty cycle, selection of converter rating, fundamental torque equation, speed torques characteristics DC motor & Induction motor, multi quadrant operation of the drive, classification of mechanical load torques, steady state stability of the drive, constant torque and constant HP operation of the drive, closed loop speed control. |   |   |                                     |           |         |  |  |  |  |
| three phases full of Multi quadrant of converter fed DC do converter fed DC s |   |   | ontrol, starting and braking operation, single phase and ontrolled and half controlled converter fed DC drives, eration of separately excited DC shunt motor, dual ives, circulating and non – circulating mode of operation, ries motor drive, chopper control of DC shunt and series hadrant operation of chopper fed DC shunt motor drive. |                                     |           | 7       |  |  |  |  |

| III   | Induction Motor Drives  Torque equation, Speed control methods for three phase cage induction motor, braking methods, stator voltage control induction motor drive, VSI fed induction motor drive, constant torque (constant E/F and constant V/F), constant HP operation, closed loop speed control block diagram, Stator current control methods fed induction motor drive, speed torque characteristics of CSI fed drive, closed loop speed control block diagram, comparison of CSI fed and VSI fed induction motor drive. | 6             |  |  |  |  |
|---|--|---------------|--|--|--|--|
| IV  | Slip Ring Induction Motor Drives  Chopper controlled resistance in rotor circuit, slip power recovery using converter cascade in rotor circuit, sub synchronous and super synchronous speed control, Kramer speed control, cyclo - converter in rotor circuit.   | 7             |  |  |  |  |
| V   | Synchronous Motor Drives and Brushless DC Motor Drives  VSI fed synchronous motor drives, true synchronous and self-control mode, open loop and closed loop speed control of Permanent magnet synchronous machine, brushless DC motor drives.  | 6             |  |  |  |  |
| VI  | Special Drives  Construction and operating principle of switched reluctance motors, Current / Voltage control, torque equation, converter circuits, operating modes and applications of switched reluctance motors. Solar panel VI characteristics, solar powered pump, maximum power point tracking and battery-operated vehicles.  | 6             |  |  |  |  |
|   | Taythaalta   |               |  |  |  |  |
| 1   | Textbooks  G. K. Dubey, "Fundamentals of Electrical Drives", Narosa publication, 2nd ed  | lition, 2002. |  |  |  |  |
|   |  |               |  |  |  |  |
| References  1 "Fundamentals of Electrical Drives", NPTEL video lecture series by Prof. Shyama Prasad Das, Department of Electrical Engineering, IIT Kanpur. |  |               |  |  |  |  |
| 2   | "Power Electronics - Converter Application", By N. Mohan T.M. Undel and W. P. Robbins, John Wiely and sons.  |               |  |  |  |  |
| 3   | "Electrical Drives - Concept and application", Vedam Subramanyam.  |               |  |  |  |  |
|   | Useful Links   |               |  |  |  |  |
| 1   | https://nptel.ac.in/courses/108/104/108104140/   |               |  |  |  |  |

| CO-PO Mapping           |   |   |   |   |   |   |  |  |  |  |
|-------------------------|---|---|---|---|---|---|--|--|--|--|
| Programme Outcomes (PO) |   |   |   |   |   |   |  |  |  |  |
|                         | 1 | 2 | 3 | 4 | 5 | 6 |  |  |  |  |
| CO1                     |   |   | 3 |   |   |   |  |  |  |  |
| CO2                     |   |   |   | 3 |   |   |  |  |  |  |
| CO3                     | 3 |   |   |   |   |   |  |  |  |  |

The strength of mapping is to be written as 1: Low, 2: Medium, 3: High Each CO of the course must map to at least one PO.

## Assessment

The assessment is based on MSE, ISE and ESE.

MSE shall be typically on modules 1 to 3.

ISE shall be taken throughout the semester in the form of teacher's assessment. Mode of assessment can be field visit, assignments etc. and is expected to map at least one higher order PO.

ESE shall be on all modules with around 40% weightage on modules 1 to 3 and 60% weightage on modules 4 to 6.

For passing a theory course, Min. 40% marks in (MSE+ISE+ESE) are needed and Min. 40% marks in ESE are needed. (ESE shall be a separate head of passing)